CENTER FOR TOKAMAK TRANSIENTS SIMULATION

VDE and RWM Status and Plans

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M3D-C1

M3D-C1 Uses Multi-Region Mesh to Model Resistive Wall

(m) Z

- Three mesh regions:
 - XMHD (extended-MHD)
 - Resistive Wall ($\mathbf{E} = \eta \mathbf{J}$)
 - Vacuum ($\mathbf{J} = 0$)
- Resistive wall is region of arbitrary thickness
- No boundary or jump conditions on ${\bf B}$ or ${\bf J}$ at the resistive wall
 - Allows Halo currents and spatially-resolved eddy currents
- Fully implicit treatment of eddy currents



Linear M3D-C1 Simulations of RWMs Successfully Validated

- Linear growth rates compared to analytic model using reduced MHD
- Agreement spans resistive-wall to inertial regimes
- Agreement for walls of arbitrary thickness





M3D-C1 Being Used for 3D Nonlinear Simulations of VDEs

- Simulations initialized with vertically unstable Grad-Shafranov Equilibrium
- Axisymmetric model is used until q_a drops and plasma becomes unstable to n > 0 modes
- Fully 3D model is then used to follow non-axisymmetric evolution of plasma and Halo currents
- See talk by D. Pfefferlé, Wednesday at 9:30 am (NI3.00001)



Primary Challenge for VDE Simulations is Resolving Gradients Near Wall

- Hot plasma touching cold wall leads to huge gradients
- Several strategies are used to mitigate this:
 - Aggressive mesh packing
 - The Schnack Protocol (*i.e.* increase viscosity when the code crashes)
 - Make wall (and SOL) artificially hot
- Artificially hot SOL makes resistivity too small
 - Stabilizing to VDE and secondary non-axisymmetric instabilities
 - We correct this by subtracting $T_{e} \, {\rm offset}$ in resistivity calculation







NIMROD

Two Resistive-Wall Formulations Have Been Implemented in NIMROD

- Both link the inner (plasma) region to an outer region via the thin resistive-wall model.
- One uses a Green's function/boundary element method that couples a NIMROD inner region to the GRIN code (Pletzer).
- The other uses a meshed outer region that solves a magnetic diffusion equation.
 - Large $\eta_{ ext{outer}}$ approximates vacuum.
 - Meshed layers of moderate $\eta_{
 m outer}$ can be used to represent a thick wall.

bc's





With the Meshed Outer Region, A Weak Form of the Thin Wall Equation is Used

 In NIMROD's weak form, the PDE from Faraday's law for the interior of each region is

$$\int_{R} \mathbf{A}^{*} \cdot \frac{\partial \mathbf{B}}{\partial t} dVol = -\int_{R} \mathbf{E} \cdot \nabla \times \mathbf{A}^{*} dVol + \oint_{\partial R} \mathbf{A}^{*} \times \mathbf{E} \cdot \hat{\mathbf{n}} dS$$

for all vector test functions

$$\mathbf{A}_{k,n,\nu}(R,Z,\phi) = \alpha_k \left[\xi(R,Z), \eta(R,Z) \right] e^{in\phi} \hat{\mathbf{e}}_{\nu}(\phi)$$

used in the expansion for the magnetic field. Here, $\alpha_k(\xi,\eta)$ is a 2D nodal spectral element, $\hat{\mathbf{e}}_1 = \hat{\mathbf{R}}(\phi)$, $\hat{\mathbf{e}}_2 = \mathbf{Z}$, $\hat{\mathbf{e}}_3 = \hat{\phi}(\phi)$, and

$$\mathbf{B}(R,Z,\phi,t) = \sum_{k,n,\nu} B_{k,n,\nu}(t) \mathbf{A}_{k,n,\nu}(R,Z,\phi)$$

The resistive-wall $\mathbf{E} = v_w \hat{\mathbf{n}} \times \delta \mathbf{B}$ is used in the surface integral.

$$v_w \equiv \frac{\eta_w}{\mu_0 \delta x}$$



Evolution of the Normal Component is Imposed as an Integral Constraint with the Same Test Functions

• Applying Faraday's law along an interface between regions, $\int_{\partial R} \mathbf{A}^* \cdot \hat{\mathbf{n}} \hat{\mathbf{n}} \cdot \frac{\partial \mathbf{B}}{\partial t} dS = -\int_{\partial R} \mathbf{A}^* \cdot \hat{\mathbf{n}} \hat{\mathbf{n}} \cdot \nabla \times \mathbf{E} dS$ $= \int_{\partial R} \hat{\mathbf{n}} \cdot \nabla \left(\mathbf{A}^* \cdot \hat{\mathbf{n}} \right) \times \mathbf{E} dS - \sum_j \oint_{\partial R_j} \mathbf{A}^* \cdot \hat{\mathbf{n}} \mathbf{E} \cdot d\mathbf{I}$

with path integrals defined by curves swept by the corners of the 2D elements.

edge of one 2D element swept over ϕ

• Adding the constraint equation with a Lagrange multiplier λ provides an unsplit relation, and E has implicit $v_w \hat{\mathbf{n}} \times \Delta \delta \mathbf{B}$ terms. $\left[\Delta f \equiv f(t + \Delta t) - f(t)\right]$

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$$\int_{R} \mathbf{A}^{*} \cdot \Delta \mathbf{B} \, dVol + \Delta t \int_{R} \mathbf{E} \cdot \nabla \times \mathbf{A}^{*} \, dVol - \Delta t \oint_{\partial R} \mathbf{A}^{*} \times \mathbf{E} \cdot \hat{\mathbf{n}} \, dS + \lambda \Big[\int_{\partial R} \mathbf{A}^{*} \cdot \hat{\mathbf{n}} \hat{\mathbf{n}} \cdot \Delta \mathbf{B} \, dS - \Delta t \int_{\partial R} \hat{\mathbf{n}} \cdot \nabla \Big(\mathbf{A}^{*} \cdot \hat{\mathbf{n}} \Big) \times \mathbf{E} \, dS + \Delta t \sum_{j} \oint_{\partial R_{j}} \mathbf{A}^{*} \cdot \hat{\mathbf{n}} \, \mathbf{E} \cdot d\mathbf{I} \Big] = 0$$



Recent Forced-VDE Computations with Asymmetric Instability use the Coupled-Region Implementation



Evolution of kinetic energy fluctuations ($0 \le n \le 10$) with $\chi_{||} = 0.75$.

• See posters CP11.00104 and CP11.00105, Monday PM, for more information



Plasma pressure at $t=250 \tau_A$ (left) and $t=500 \tau_A$ (right).





Plans

Three Areas of Development Are Needed for VDE Studies

- 1. Sheath boundary conditions
 - Results are sensitive to conditions for *T* along wall.
 - Loizu, *et. al.* (PoP **19**, 122307) formulated bc's for reduced turbulence modeling.
 - We are adapting these conditions and will implement.
- 2. Wall geometry
 - Many NIMROD tokamak computations use conformal meshes outside the separatrix.
 - Special cross-section shapes have been meshed by hand.
 - Development of spectral triangles or blocks of unstructured quads will facilitate application to experiments.
- 3. Implicit advances
 - 3D simulation over long times (CQ) encounter many dynamics.
 - A-stable methods may facilitate computations by suppressing unimportant fluctuations.



For RWM Studies, We Proposed to Incorporate Kinetic Effects

- The wall modeling described earlier is suitable for RWM studies.
- Meshing developments would also benefit RWM applications.
- Kinetic effects are considered important for RWM stability properties [Berkery, et. al. PoP 17, 082504].
 - We proposed to apply NIMROD's drift-kinetic modeling.
 - To date, there have been no attempts to invoke both RW and DKE in a computation.
 - The Green's function approach may be the easier starting point.



M3D-C1 Development Will Include Radiation Models and Wall Asymmetries

- Implementation of KPRAD module in M3D-C1 is underway
 - Will track charge states and radiation from one impurity species
- Will implement non-axisymmetric wall structures by using a nonaxisymmetric wall resistivity
 - Mesh will remain axisymmetric
 - Presently have capability for rectangular (in (R, ϕ, Z) coordinates) ports / breaks
- Particle source as a function of halo current may be necessary to capture halo current rotation

VDE Benchmark Should Test Primary Physical Prediction Targets

- Linear growth rate of VDE
- Halo currents as a function of time and space
- Plasma current and q-profile evolution during CQ
- Sideways (n = 1) forces, and rotation of these forces
- Is comparison of unstable VDE calculations a viable near term goal?
 - We have many DIII-D and NSTX geqdsks available (n = 0 so results shouldn't depend strongly on getting perfect equilibrium match)
 - Start with axisymmetric model
 - Can use an analytic (Miller-like) wall shape

RWM Benchmark Could Focus on Braking

- RWM benchmark doesn't need to be a resistive wall mode
 - Could be resistive wall tearing mode, or other mode that penetrates wall
 - Tearing mode rotates with plasma; RWM rotates at resistive wall frequency
- Focusing on braking would make benchmark interesting
 - Mode causes plasma to slow down by interaction of response fields with eddy currents
 - Not the same as ongoing error field penetration benchmark, which does not involve a resistive wall
 - Could start with case like Matt Beidler's (straight cylinder, circular cross-section), but unstable and without RMPs.