

Update on NTM Modeling Using Heuristic Closures

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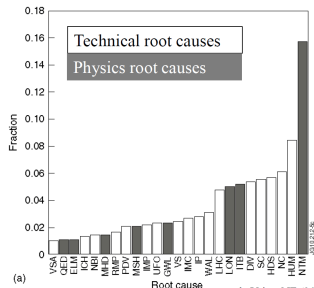
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- 1 Introduction
- 2 Model Equilibria
- 3 Heuristic Closures
- 4 Conclusions and Future Work

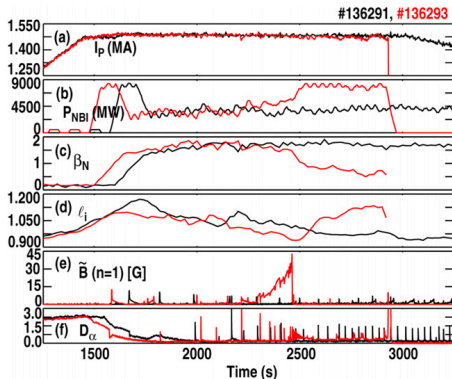
- Ideal MHD limits are relatively well-understood: $\beta_N \lesssim 4l_i$
- Rotating tearing modes result in a soft β limit: $\beta_N \lesssim 2l_i$
- Locked modes are a leading cause of disruptions



P. de Vries, NF 2011

NTM Modeling is Computationally Challenging due to their Slow Evolution and Kinetic Nature

- Evolution spans multiple ELM and sawtooth cycles
 - τ_{ntm} : 100 – 1000ms
 - τ_{elm} : 5 – 20ms
 - τ_{saw} : 100ms
- Neoclassical effects govern island evolution
 - Self-consistent modeling requires solving 5D DKE



F. Turco NF 2010

Our Numerical Simulations do not Model the Experimental Control Systems

- NTM control is routine on large experiments
 - ECCD, entrainment and spin-up
 - Disruption threshold depends on MHD and control system
- Experiments are preemptively terminated when large amplitude locked modes are observed
 - Decrease I_p , turn off heating
 - Changes to actuators alters dynamics
 - Muddies validation

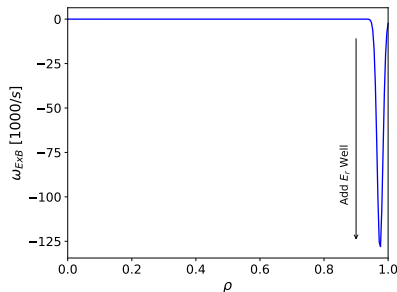
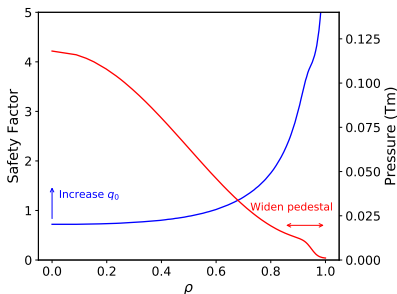
Our Approach to Studying NTM Disruptions

- Construct experimentally relevant model equilibria
 - Start from approximate DIII-D ITER baseline discharge
 - Modify equilibria to remove extraneous dynamics
- Use heuristic closures to model neoclassical stresses
 - Heuristic closures model dominant neoclassical effects
 - Use model parameters to scale island width
- Investigate how locked NTM cause disruption

Generation of Model Equilibria

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Model Equilibria are Created to Focus on NTMs



- Raise $q_0 > 1$ to avoid sawteeth
- Widen pedestal and add E_r well to stabilize edge modes
- Increase λ locally to increase Δ'

Proportional-Derivative Feedback System Implemented for Shape Control

- External currents are updated using a PD controller:

$$\delta I_j^n = \alpha_p J_{ji}^{(k)\sim 1} e_i^n + \alpha_d J_{ji}^{(k)\sim 1} (e_i^n - e_j^{n-1})$$

Shape control points: $\{r_i\}$

Flux on control surface: ψ_0

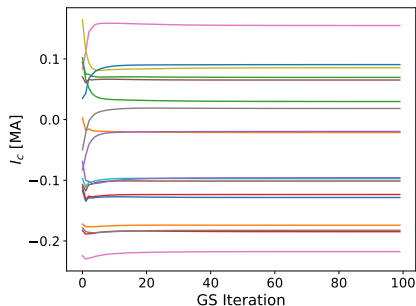
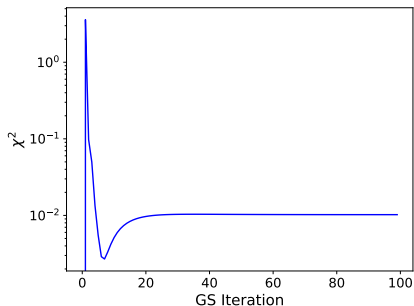
Square error: $e_i^2 = w_i (\psi(r_i) - \psi_0)^2$

Jacobian: $J_{ij} = \frac{\partial e_i}{\partial I_j} \equiv U \Sigma V^T$

SVD pseudo-inverse:² $J^{(k)\sim 1} \equiv V \Sigma^k U^T$

²J. D. Hanson NF 2009

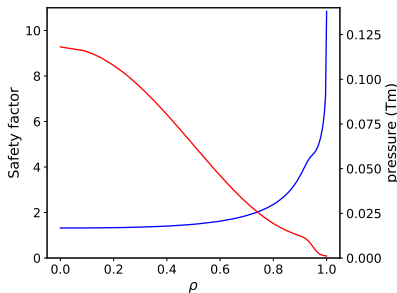
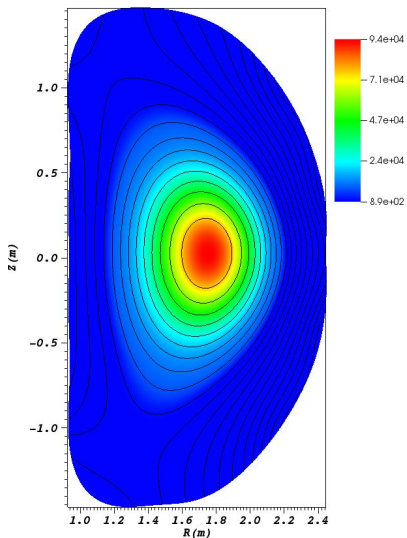
Example Case Illustrates the Performance of the Feedback System



- 100 control points specify the $\hat{\psi} = 0.95$ surface
- Provides vertical and radial stability
- Performance is sensitive to the number of singular values
 - A cutoff tolerance of 10^{-4} works well

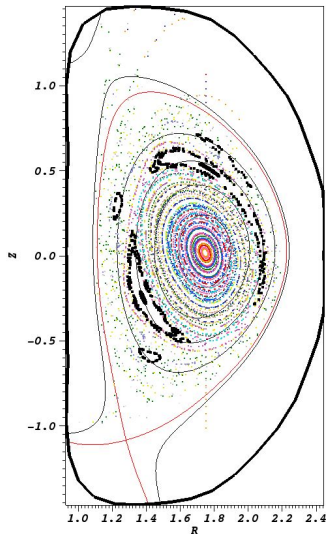
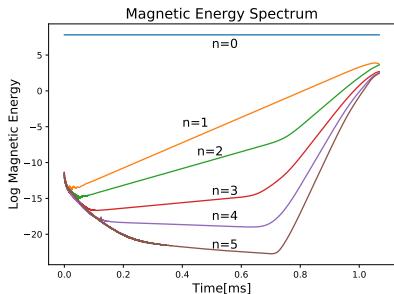
Modifications Enable Creation of ITER-Like Equilibria

Equilibrium Pressure(Pa)



I_p	0.958 MA
ϵ	0.33
κ	1.83
q_0	1.32
q_{95}	5.2
β_N	1.85
β_N/l_i	2.31

Equilibria is $n = 1$ Tearing Unstable



S	10^5
Pr_m	10
ν_{visc}/χ_{\perp}	1
k_{\parallel}/k_{\perp}	10^4

Numerical Implementation and Testing of Heuristic Closures

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Neoclassical Effects Modify MHD Through the Stresses (and Heat Fluxes)

Continuity:
$$\frac{\partial n}{\partial t} + \vec{v} \cdot \nabla n = n \nabla \cdot \vec{v}$$

Momentum:
$$\rho \left(\frac{\partial \vec{v}}{\partial t} + \vec{v} \cdot \nabla \vec{v} \right) = \vec{J} \times \vec{B} - \nabla p - \nabla \cdot \vec{\Pi}_\nu - \nabla \cdot \vec{\Pi}_i$$

Temperature:
$$\frac{n}{\Gamma-1} \left(\frac{\partial T}{\partial t} + \vec{v} \cdot \nabla T \right) = -nT \nabla \cdot \vec{v} - \nabla \cdot \vec{q} + Q$$

Faraday's Law:
$$\frac{\partial \vec{B}}{\partial t} = -\nabla \times \vec{E}$$

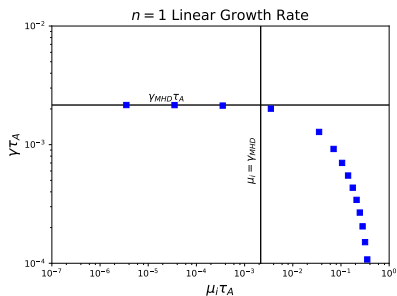
Ohm's Law:
$$\vec{E} = -\vec{v} \times \vec{B} + \eta \vec{J} - \frac{1}{ne} \nabla \cdot \vec{\Pi}_e$$

$$\nabla \cdot \vec{\Pi}_i = nm_i \mu_i \langle B^2 \rangle \frac{\vec{v} \cdot \vec{e}_\Theta}{(\vec{B} \cdot \vec{e}_\Theta)^2} \vec{e}_\Theta$$
$$\nabla \cdot \vec{\Pi}_e = -\frac{nm_e \mu_e}{ne} \langle B^2 \rangle \frac{\vec{J} \cdot \vec{e}_\Theta}{(\vec{B} \cdot \vec{e}_\Theta)^2} \vec{e}_\Theta$$

- Heuristic closures model dominant neoclassical effects³
 - Poloidal ion flow damping
 - Enhancement of polarization current
 - Bootstrap current

³Gianakon, POP 9, 2002

Neoclassical Enhancement of the Polarization Current is Used to Test the Ion Stress



S	10^5
Pr_m	1
ν_{visc}/χ_{\perp}	1
k_{\parallel}/k_{\perp}	10^8
μ_e	0

- The ion stress damps poloidal flows associated with tearing modes
- Damping increases inertia by a factor of $\left(1 + C \frac{\mu_i}{\gamma}\right)$
- Growth rate is reduced when $\mu_i \gtrsim \gamma_{MHD}$

- Modifications enable the generation of experimentally relevant equilibria
 - New feedback system enables shape control
 - Equilibria designed to focus on NTM physics
- Heuristic closures are used to model neoclassical stresses
 - Tests of the closures are ongoing
- Modifications will be used to investigate the mechanisms by which NTMs cause disruptions